

# Nematic Liquid Crystals: Soft Matter Meets Elasticity and Geometry

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## *Summary*

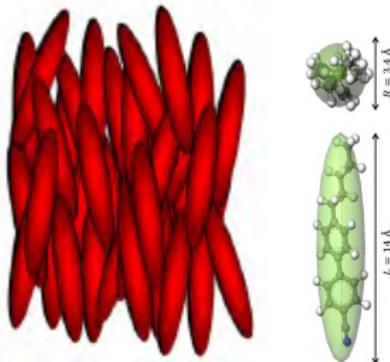
*Nematic Liquid Crystals*  
*Curvature Elasticity*  
*Elementary Distortion Modes*  
*Uniform Distortions*  
*Generalized Elasticity*  
*Conclusions*

## Nematic Liquid Crystals

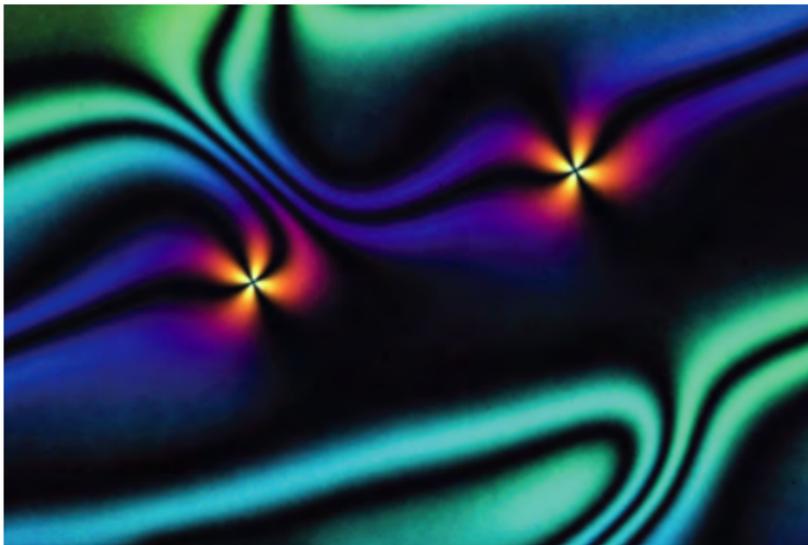
We use the notion of *uniform distortion* in the mathematical theory of *nematic liquid crystals* to illustrate the interplay between Elasticity and Geometry in Soft Matter.

### *lexicon*

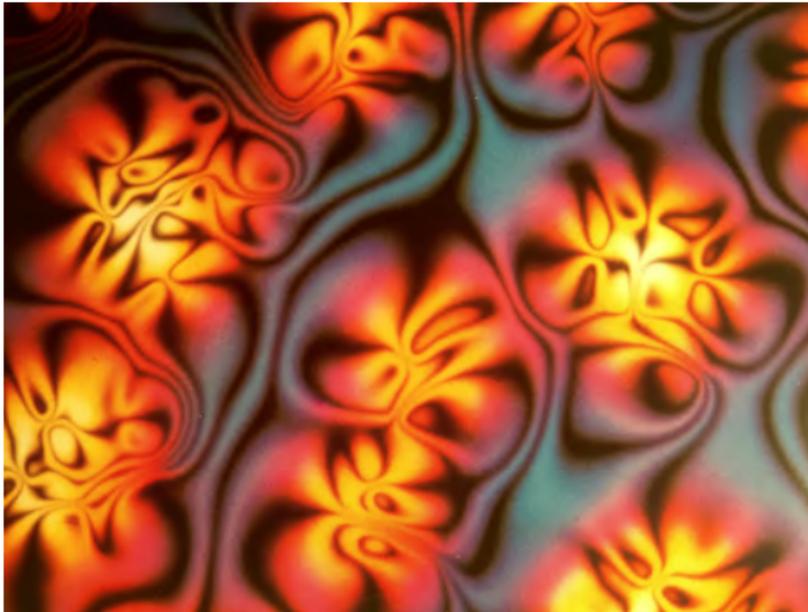
- ▶ Liquid crystals are *anisotropic* fluids.
- ▶ The *nematic* phase is *typically* produced by the *ordered* assembly of elongated, *rod-like* molecules, which are on *average* aligned along the *director*  $n$ .



- ▶ The director  $\mathbf{n}$  is a unit vector; it resides in the unit sphere  $\mathbb{S}^2$ .
- ▶ Nematic liquid crystals are *birefringent*; their *optic axis* coincides with  $\mathbf{n}$  and can *easily* vary in space.
- ▶ For rod-like nematics, a *natural state* is any *uniform* director field, for which  $\nabla\mathbf{n} \equiv \mathbf{0}$ .
- ▶ Nematic liquid crystals are *not polar*; the theories that describe them must be *indifferent* to changing  $\mathbf{n}$  into  $-\mathbf{n}$ .
- ▶ A *defect* is a *singularity* of  $\mathbf{n}$ .
- ▶ Defects are *optically* detectable.



Courtesy of O.D. LAVRETOVICH



Courtesy of O.D. LAVRETOVICH

### *early statistical theories*

The phase transition from *isotropic* to *nematic*—driven by concentration (*lyotropic*) or temperature (*thermotropic*)—was described by two pioneering theories:

- ▶ **ONSAGER (1949)**: purely entropic *ordering* forces based on short-range mutual repulsion of molecules.
- ▶ **MAIER & SAUPE (1958)**: mean field model based on long-range mutual attractive *dispersion* London forces.
- ▶ **DE GENNES (1969, 1971)**: Landau theory based on a *tensorial* order parameter.

## Curvature Elasticity

The curvature elasticity of liquid crystals in *three dimensions* is based on a free-energy functional introduced by FRANK (1958), which falls within the larger class envisaged by ERICKSEN (1962).

### *elastic free energy*

The elastic free-energy functional measures the cost associated with producing a *distortion* in a natural state.

$$\mathcal{F}[n] = \int_{\mathcal{B}} W(\mathbf{n}, \nabla \mathbf{n}) \, dV$$

$\mathcal{B}$  domain in space

$V$  volume measure

$W$  elastic free-energy density

$W$  is *frame-indifferent*

$$W(\mathbf{Q}\mathbf{n}, \mathbf{Q}\nabla\mathbf{n}\mathbf{Q}^T) = W(\mathbf{n}, \nabla\mathbf{n}) \quad \forall \mathbf{Q} \in \mathbf{O}(3)$$

$W$  is *even*

$$W(-\mathbf{n}, -\nabla\mathbf{n}) = W(\mathbf{n}, \nabla\mathbf{n})$$

### *Frank's formula*

The most general frame-indifferent and even function  $W$  that is at most *quadratic* in  $\nabla \mathbf{n}$  was obtained by FRANK (1958),

$$W_F(\mathbf{n}, \nabla \mathbf{n}) = \frac{1}{2}K_1(\operatorname{div} \mathbf{n})^2 + \frac{1}{2}K_2(\mathbf{n} \cdot \operatorname{curl} \mathbf{n})^2 + \frac{1}{2}K_3|\mathbf{n} \times \operatorname{curl} \mathbf{n}|^2 \\ + K_{24}(\operatorname{tr}(\nabla \mathbf{n})^2 - (\operatorname{div} \mathbf{n})^2)$$

$K_i$  Frank's elastic constants

$K_1$  splay constant

$K_2$  twist constant

$K_3$  bend constant

$K_{24}$  saddle-splay constant

### *Ericksen's inequalities*

$W_F(\mathbf{n}, \nabla \mathbf{n}) \geq 0$  a.e.  $\forall \mathbf{n} \in H^1(\mathcal{B}; \mathbb{S}^2)$  iff

$$K_3 \geq 0, \quad K_2 \geq K_{24}, \quad K_1 \geq K_{24} \geq 0$$

ERICKSEN (1966)

## Elementary Distortion Modes

Recently, a fresh look into this established theory has revealed unexpected scenarios.

MACHON & ALEXANDER (2016), SELINGER (2018)

### *distortion decomposition*

$$\nabla \mathbf{n} = -\mathbf{b} \otimes \mathbf{n} + \frac{1}{2}T\mathbf{W}(\mathbf{n}) + \frac{1}{2}S\mathbf{P}(\mathbf{n}) + \mathbf{D}$$

$S := \operatorname{div} \mathbf{n}$  splay scalar

$T := \mathbf{n} \cdot \operatorname{curl} \mathbf{n}$  twist pseudoscalar

$\mathbf{b} := \mathbf{n} \times \operatorname{curl} \mathbf{n}$  bend vector

$\mathbf{W}(\mathbf{n})$  skew tensor associated with  $\mathbf{n}$

$\mathbf{P}(\mathbf{n}) := \mathbf{I} - \mathbf{n} \otimes \mathbf{n}$  projector tensor

$\mathbf{D}$  octupolar splay tensor

### *octupolar splay*

$$\mathbf{D} = q(\mathbf{n}_1 \otimes \mathbf{n}_1 - \mathbf{n}_2 \otimes \mathbf{n}_2)$$

$q$  *positive* eigenvalue of  $\mathbf{D}$

### *identity*

$$2q^2 = \text{tr}(\nabla \mathbf{n})^2 + \frac{1}{2}T^2 - \frac{1}{2}S^2$$

The four components of  $\nabla \mathbf{n}$  are *independent* from one another.

- ▶ *distortion frame*: the eigenvectors  $(\mathbf{n}_1, \mathbf{n}_2, \mathbf{n})$  of  $\mathbf{D}$  for  $q > 0$ .
- ▶ *distortion measures*: the list  $(S, T, \mathbf{b}, \mathbf{D})$ .
- ▶ *distortion characteristics*: the scalars  $(S, T, b_1, b_2, q)$ .

$$\mathbf{b} = b_1 \mathbf{n}_1 + b_2 \mathbf{n}_2$$

### *Frank's free energy*

$$W_F = \frac{1}{2}(K_{11} - K_{24})S^2 + \frac{1}{2}(K_{22} - K_{24})T^2 + \frac{1}{2}K_{33}B^2 + 2K_{24}q^2$$

$$B^2 := \mathbf{b} \cdot \mathbf{b}$$

## *Modes illustration*

The four independent modes can be illustrated pictorially.

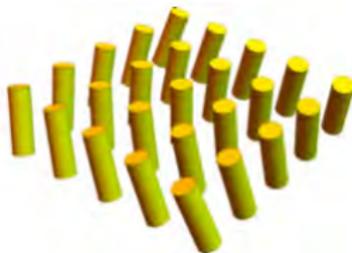
SELINGER (2021)

### *splay mode*



$$S \neq 0 \quad T = 0 \quad B = 0 \quad q = 0$$

### *(double) twist mode*



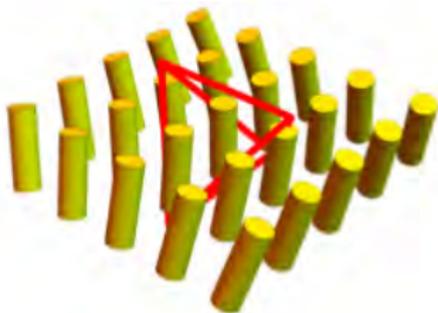
$$S = 0 \quad T \neq 0 \quad B = 0 \quad q = 0$$

*bend mode*



$$S = 0 \quad T = 0 \quad B \neq 0 \quad q = 0$$

*octupolar splay mode*



$$S = 0 \quad T = 0 \quad B = 0 \quad q \neq 0$$

## *octupolar representation*

An alternative representation, suggested by the octupolar splay mode, is offered for all modes but the (double) twist by an *octupolar tensor*. GAETA & VIRGA (2016, 2019) PEDRINI & VIRGA (2020)

$$\mathbf{A} := \overline{\nabla \mathbf{n} \otimes \mathbf{n}}$$

$\overline{\dots}$  irreducible part of a tensor

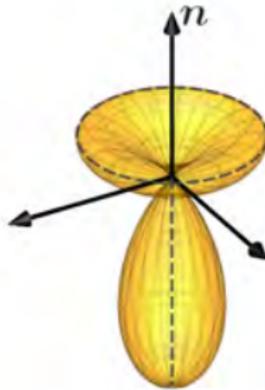
## *octupolar potential*

$$\Phi(\mathbf{x}) := \mathbf{A} \cdot \mathbf{x} \otimes \mathbf{x} \otimes \mathbf{x} = \sum_{i,j,k=1}^3 A_{ijk} x_i x_j x_k$$

$\mathbf{x} = x_1 \mathbf{n}_1 + x_2 \mathbf{n}_2 + x_3 \mathbf{n}$  on the unit sphere  $\mathbb{S}^2$

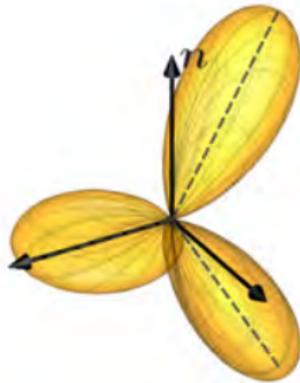
$$\begin{aligned} \Phi(\mathbf{x}) &= \left( \frac{S}{2} + q \right) x_1^2 x_3 + \left( \frac{S}{2} - q \right) x_2^2 x_3 - b_1 x_1 x_3^2 - b_2 x_2 x_3^2 \\ &+ \frac{1}{5} (x_1^2 + x_2^2 + x_3^2) (b_1 x_1 + b_2 x_2 - S x_3) \end{aligned}$$

*polar plots*



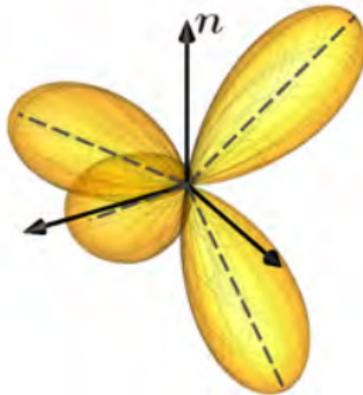
*splay mode*

*polar plots*



*bend mode*

*polar plots*



*octupolar splay mode*

## Uniform Distortions

On a *smooth* (not necessarily flat) *surface* embedded in 3D *Euclidean* space,

$$T \equiv 0 \quad \text{and} \quad \mathbf{D} \equiv \mathbf{0}$$

*geometric compatibility*

$$K = -S^2 - B^2 - \nabla S \cdot \mathbf{n} + \nabla B \cdot \mathbf{n}_\perp$$

$K$  Gaussian curvature

$\nabla$  covariant derivative

$\mathbf{n}_\perp := \mathbf{N}\mathbf{n}$  unit vector orthogonal to  $\mathbf{n}$

$\mathbf{N}$  skew tensor associated with  $\nu$

$\nu$  normal to the surface

NIV & EFRATI (2018)

*consequences*

- ▶ The field  $\mathbf{n}$  can be uniquely *reconstructed* from the sole knowledge of  $S$  and  $B$ , provided that  $|\nabla S + \mathbf{N}\nabla B| > |S^2 + B^2 + K|$  POLLAR & ALEXANDER (2021)
- ▶ Only *hyperbolic* geometries can host *uniform* distortions in 2D.

### *questions*

- ▶ How to define *uniformity* in 3D?
- ▶ Is it possible to fill space with a combination of *uniform* modes?

### *comment*

Both questions border on the notion of eligible *ground states* meant as the ones suffering *no* geometric *frustration*.

### *uniform distortion*

A field  $\mathbf{n}$  such that its distortion characteristics  $(S, T, b_1, b_2, q)$  are the *same* everywhere, although the distortion frame  $(\mathbf{n}_1, \mathbf{n}_2, \mathbf{n})$  may not be.

### *lost in space*

For such a field, we could not tell *where we are* in space only by sampling the local nematic distortion.

### 3D Euclidean space

There are only *two families* of possible uniform distortions that fill 3D Euclidean space:

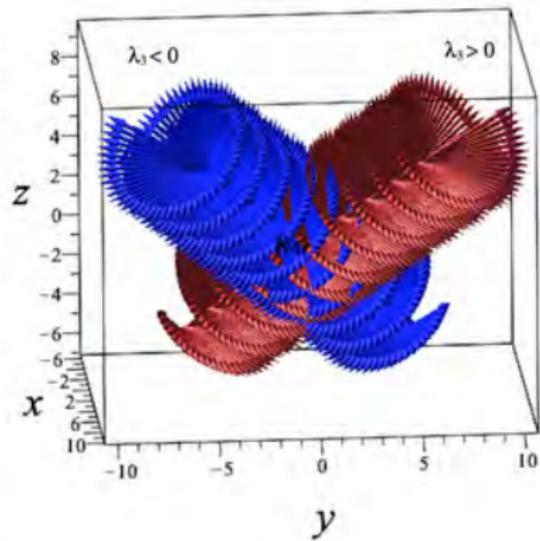
$$\begin{aligned} S = 0, \quad T = 2q, \quad b_1 = b_2 = b \\ S = 0, \quad T = -2q, \quad b_1 = -b_2 = b \end{aligned}$$

They correspond to *foliations* of 3D Euclidean space in *parallel helices*. VIRGA (2019)

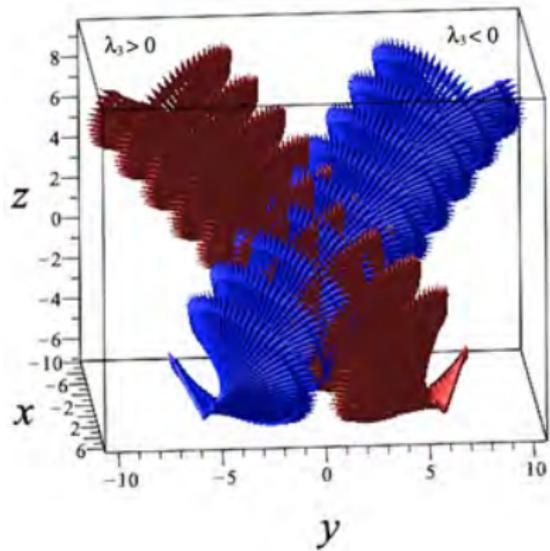
### heliconical fields

The director  $\mathbf{n}$  makes a constant *conical* angle  $\theta$  with the *axis* of a *helix* with *pitch*  $p$ :

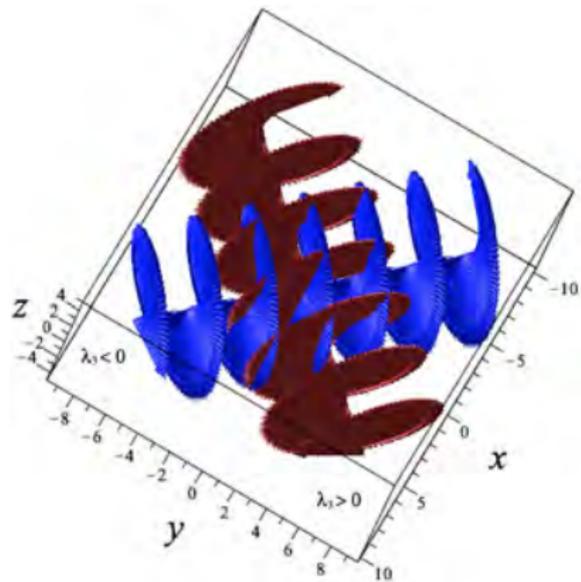
$$\begin{aligned} \cos \theta &= \frac{|b|}{\sqrt{b^2 + 2q^2}} \\ p &= \frac{2\pi}{|\lambda_3|} \quad \lambda_3 = \pm \left( 2q + \frac{b^2}{q} \right) \end{aligned}$$



$$b/q = -1$$



$$b/q = 1$$



$$b = 0$$

## Non-Euclidean 3D spaces

The quest for *uniform distortions* has recently been also conducted in *3D Riemannian manifolds* within CARTAN's *moving frame* formalism.

POLLARD & ALEXANDER (2021)

DA SILVA & EFRATI (2021)

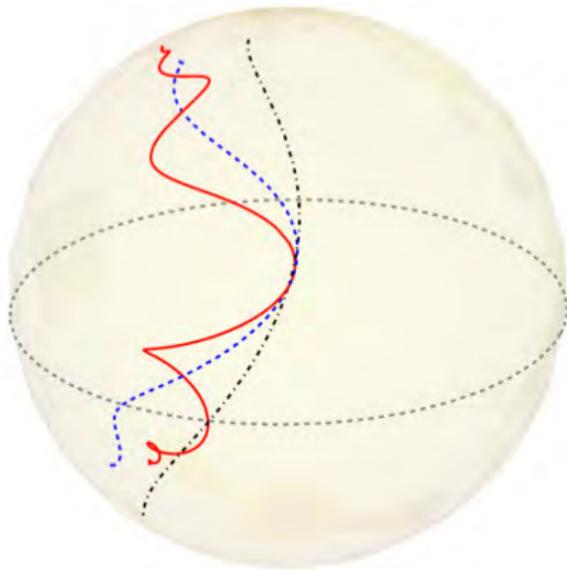
- ▶ Each pure distortion mode, characterized by a single non-vanishing component of  $(S, T, b_1, b_2, q)$ , can *fill space* without frustration in at least *one* of the eight *Thurston geometries*.  
SADOC, MOSSERI & SELINGER (2020)
- ▶ It had already been shown that the *double twist* mode  $T \neq 0$ , resulting in the *frustrated* cholesteric *blue phases*, can be accommodated in a three-dimensional *spherical geometry*.  
SETHNA, WRIGHT & MERMIN (1983)
- ▶ Consider a 3D *manifold* with *Riemannian tensor*

$$R_{ijkl} = R_0(\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk})$$

If  $R_0 > 0$ , the *double twist* mode is the *only* uniform distortion.  
If  $R_0 < 0$ , *all uniform distortions* provide a *foliation* of space by *non-parallel* congruent *helices*.

DA SILVA & EFRATI (2021)

## *Poincaré ball representation*



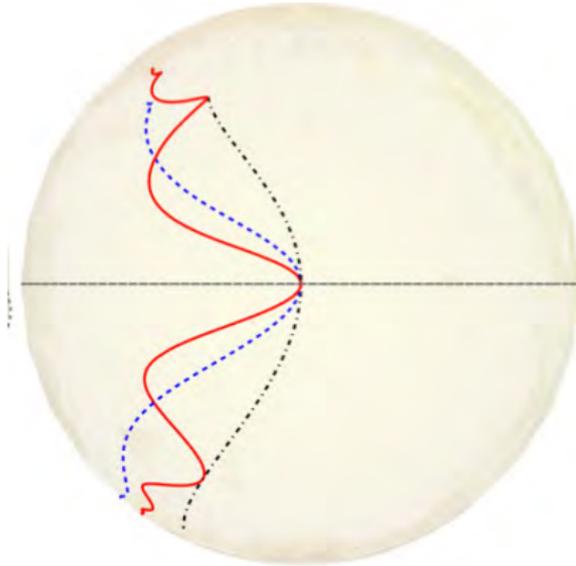
$$B < \sqrt{-R_0}$$

$$B = \sqrt{-R_0}$$

$$B > \sqrt{-R_0}$$

DA SILVA & EFRATI (2021)

*side view*



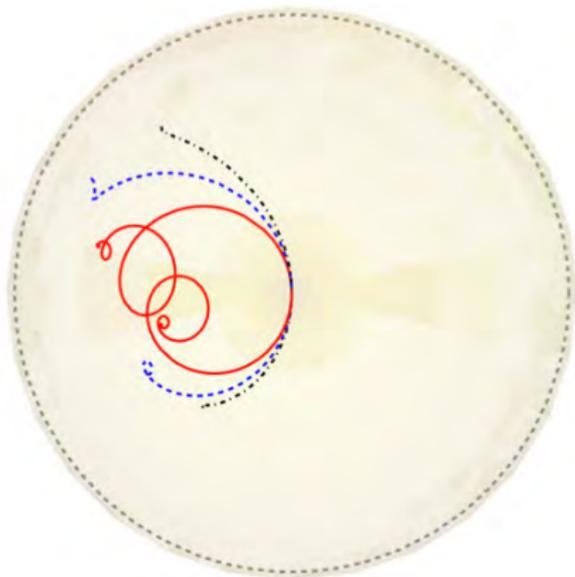
$$B < \sqrt{-R_0}$$

$$B = \sqrt{-R_0}$$

$$B > \sqrt{-R_0}$$

DA SILVA & EFRATI (2021)

*top view*



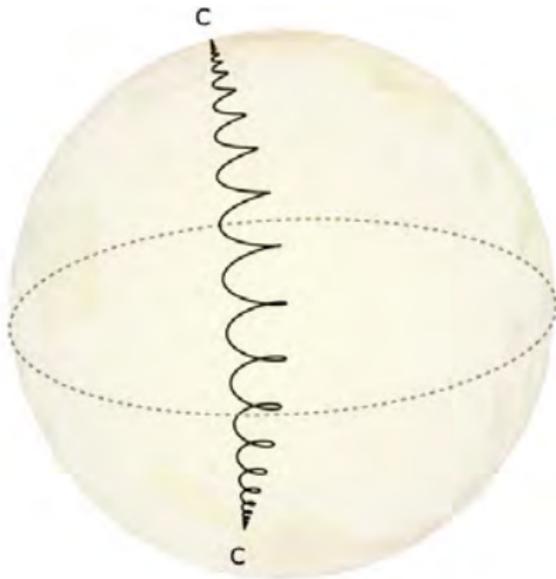
$$B < \sqrt{-R_0}$$

$$B = \sqrt{-R_0}$$

$$B > \sqrt{-R_0}$$

DA SILVA & EFRATI (2021)

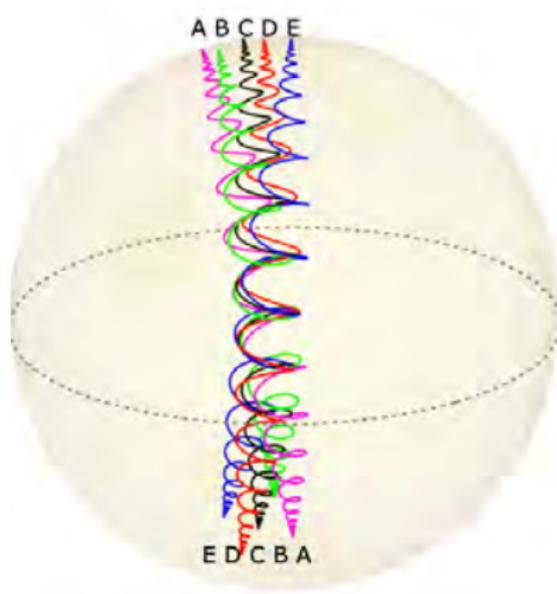
*helices foliation*



$$B > \sqrt{-R_0}$$

DA SILVA & EFRATI (2021)

*helices foliation*



$$B > \sqrt{-R_0}$$

DA SILVA & EFRATI (2021)

## Generalized Elasticity

*Uniform distortions* are natural *ground state* candidates for *novel phases*, irrespective of the free-energy model in use.

### *twist-bend phases*

The *helical* distortion was first considered by MEYER (1976) as a possible ground state, in view of its ability to fill space.

Recently, this phase has been found experimentally in *bent-core dimers*.

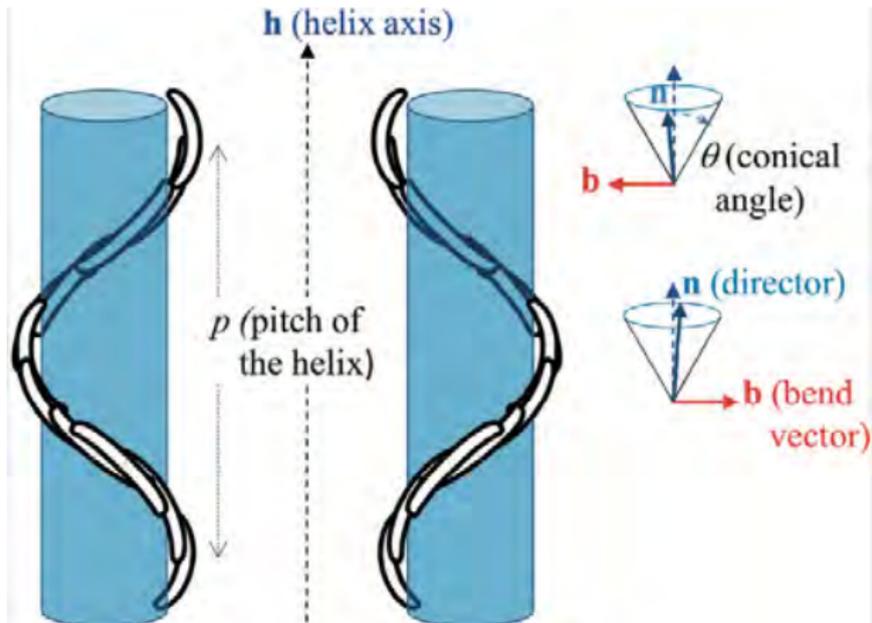
CESTARI, DIEZ-BERART, DUNMUR, FERRARINI, DE LA FUENTE, JACKSON, LOPEZ, LUCKHURST, PEREZ-JUBINDO, RICHARDSON, SALUD, TIMIMI & ZIMMERMANN (2011)

There is still an active debate on the origin of the phase, but its existence is no longer questioned.

SAMULSKI, VANAKARAS & PHOTINOS (2020)

DOZOV & LUCKHURST (2020)

*microscopic picture*



DOZOV & LUCKHURST (2020)

The modulated arrangement in a twist-bend phase is *not* accompanied by a *mass density wave*.

CHEN, PORADA, HOOPER, KLITTNICK, SHEN, TUCHBAND, KORBLOVA, BEDROV, WALBA, GLASER, MACLENNAN & CLARK (2013)

*double-well free energy*

$$W_{TB}(S, T, b_1, b_2, q) := \frac{1}{2}k_1 S^2 + \frac{1}{2}k_2 \left( T^2 + (2q)^2 \right) + \frac{1}{2}k_3 B^2 \\ + \frac{1}{4}k_4 \left( T^4 + (2q)^4 \right) + \frac{1}{4}k_5 B^4 - k_6 (2q) T b_1 b_2$$

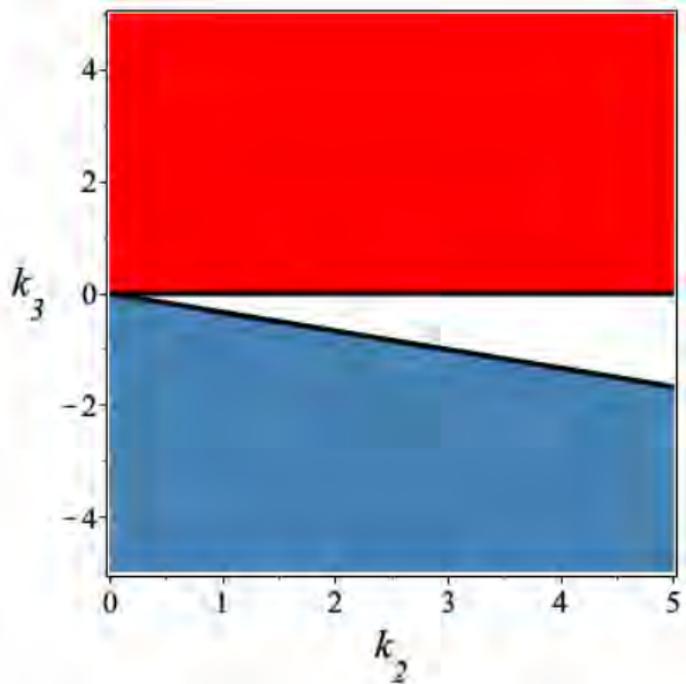
*invariance requirements*

$$(2q)T \rightarrow -(2q)T \quad b_1 b_2 \rightarrow -b_1 b_2$$

*objective form*

$$2qb_1 b_2 = \operatorname{curl} \mathbf{n} \cdot (\nabla \mathbf{n}) \mathbf{b} + \frac{1}{2} T B^2$$

*phase diagram*



$$k_3 = -2 \frac{k_5}{k_6} k_2$$

*Uniform constant*

*Non-uniform bend*

*Uniform twist-bend*

VIRGA (2019)

## Conclusions

- ▶ The notion of *uniform distortion* has been illustrated for liquid crystals, but it is far more general: it can be applied to other *soft matter* domains with *order parameters* of a different kind.
- ▶ The *lack* of uniformity in the *ground state* entails *geometric frustration*, which results in *residual stresses* and *super-extensivity* of the free-energy functional, which may cause *defects* to arise. MEIRI & EFRATI (2021)
- ▶ *Chromonic* liquid crystals, which are dyes widely used in the food industry, are *frustrated* as their ground state is the pure *double twist*  $T \neq 0$ , which is *not* uniform. PAPARINI & VIRGA (2021)

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### *Discussion*

J. V. SELINGER



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DI PAVIA

### *Soft Matter Mathematical Modelling*

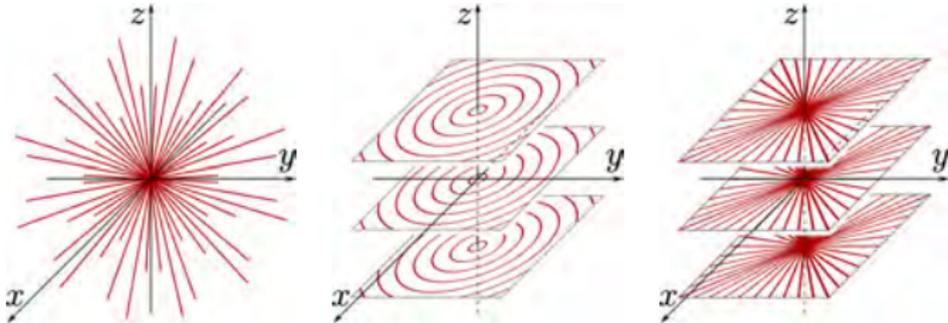
Department of Mathematics  
University of Pavia, Italy

## *Addendum: Quasi-uniform distortions*

A distortion is *quasi-uniform* if its characteristics are in *constant* ratio to one another. PEDRINI & VIRGA (2020)

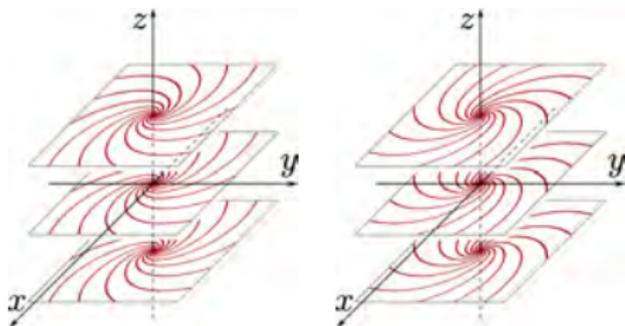
The distortion landscape is the same everywhere, to within a *scaling* factor depending on *position*.

### *simple examples*



These distortions are all *universal solutions* according to ERICKSEN (1967).

*non-universal ones*



*more generally*

Any unit vector field which is a constant combination of

$$\mathbf{e}_1 = \cos g(z)\mathbf{e}_x + \sin g(z)\mathbf{e}_y, \quad \mathbf{e}_2 = -\sin g(z)\mathbf{e}_x + \cos g(z)\mathbf{e}_y, \quad \mathbf{e}_3 = \mathbf{e}_z$$

$g(z)$  antiderivative of the scaling function

*quasi-uniform heliconal*

$$\cos \theta \mathbf{e}_z + \sin \theta (\cos g(z)\mathbf{e}_x \pm \sin g(z)\mathbf{e}_y)$$

POLLAR & ALEXANDER (2021)

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